Available Models

Unit type		Inputs	Outputs	Clock	Model number
10 I/O points 6 inputs; 4 outputs	Connector	6, 24- VDC inputs	4 transistor (sinking) outputs	0	CPM2C-S100C-DRT
			4 transistor (sourcing) outputs	0	CPM2C-S110C-DRT

Dimensions (mm)



DeviceNet is a registered trademark of the ODVA (Open DeviceNet Vendor Association, Inc.).

CompoBus/D is a trademark used for OMRON products that conform to DeviceNet standards.

All CompoBus/D-series products conform to DeviceNet standards.





Note: Do not use this document to operate the Unit.

OMRON Corporation FA Systems Division H.Q. 66 Matsumoto Mishima-city, Shizuoka 411-8511 Japan Tel:(81)559-77-9181 Fax:(81)559-77-9045

Regional Headquarters OMRON EUROPE B.V. Wegalaan 67-69, NL-2132 JD Hoofddorp The Netherlands Tel:(31)2356-81-300/Fax:(31)2356-81-388 **OMRON ELECTRONICS, INC.** 1 East Commerce Drive, Schaumburg, IL 60173 U.S.A. Tel:(1)847-843-7900/Fax:(1)847-843-8568

OMRON ASIA PACIFIC PTE. LTD. 83 Clemenceau Avenue #11-01, UE Square, Singapore 239920 Tel: (65)835-3011/Fax: (65)835-2711 Authorized Distributor:

Note: Specifications subject to change without notice.

Cat.No.R071-E1-1 Printed in Japan 1100-5M

OMRON

Programmable Slaves

A slave with the complex functionality needed for distributed blocks. Programmable Slaves

Programmable Slaves combine devices, such as sensors and actuators, into one functio nal unit that is treated as a DeviceNet slave. Programmable Slaves greatly facilitate device distribution and functional organization.

They help standardize programming between units and reduce the amount of programming required at the master. I/O and operational checks can be performed for each functional unit, rather than waiting for final system assembly, as with conventional distributed I/O systems.

Functions

OMRON Programmable Slaves function as DeviceNet slaves, vet they provide PLC functionality to enable easy system expansion and create new potential.







Connected to bar code readers, Programmable Terminals,

protocol munica- ions	NT Links	Host Links	
-----------------------------	----------	------------	--

Programmable Slaves Increase Distributed Control Potential

Slaves with **Composite Functionality**

Gateway

Implementing Mechanical Operations as Objects

Combining the Programmable Slave's intelligent functions enables an entire mechanical unit to be designed with one slave. Using Programmable Slaves for distributed control allows mechanical operations to be treated as objects and enables programming using "programming components." These features make it far easier to modify and improve devices and systems. And because a Programmable Slave functions as a slave in a DeviceNet open network, a master made by another company can also be used.



Gateway Functions

Using a Programmable Slave enables a wide variety of CompoBus/S inputs and outputs to be connected to a DeviceNet network.

I/O control for 256 I/O points (128

When the maximum of 63 Programmable Slaves are connected to a DeviceNet network, control of more than 16,000 I/O points on 2,016 eight-point CompoBus/S slaves (1,008 input slaves/1,008 output slaves) can be controlled with one Device-Net master. (See note 2.)

Units and I/O points for which control is possible will be less than that stated above when using the C200HW-DRM21-V1 or CVM1-DRM21-V1, which are currently available.

System Device Configuration



2 ms

Replacement of Logic Boards

High-speed processing compensates for the delay time in network communications. A scan time of up to 2 ms is possible with a 500-step program. (See note 3.) With 50-µs quick-response inputs and interrupt inputs, control requiring precise timing can be performed from a slave. The Programmable Slave has a built-in high-speed counter, with a maximum input of 20 kHz. Use the counter with interrupt inputs to generate control interrupts when the count matches a set value.

Note 3: The above figure applies for programming with basic instructions only. In CompoBus/S Long-distance Communications Mode, the scan time is 7 ms min.

Mainte-

Shunting Operation for Communications Errors and Preventive Maintenance







The Programmable Slave boasts 50-µs guick-response inputs and a scan time of 2 ms max. for 500-step operation. Interrupt inputs provide the high mechanical speed required for improved

A single-axis high-speed counter provides a response frequency of 20 kHz (single-phase) or 5 kHz (2-phase), and a 2-axis highspeed counter provides a response frequency of 2 kHz (singlephase only)

Choose from two, single-phase pulse outputs with no acceleration/deceleration, two pulse outputs with variable duty-ratio, or trapezoid acceleration/deceleration outputs (one pulse and direction output and one incrementing/decrementing pulse output). Either absolute or relative coordinates can be used for the coordinate system for pulse outputs (set in the PC Setup).

Functions



Interrupt inputs provide what's necessary to program high-speed response. The Programmable Slave has two separate interrupt inputs (both inputs can be used for either quick-response inputs or interrupt inputs in counter mode) with a minimum input signal width of 50 us and a response time of 0.3 ms. When an interrupt input turns ON, the program is interrupted to execute the interrupt program.

A total of 256 timers and counters are available, including 1-ms, 10-ms, 100-ms, and 1-s/10-s timers, and decrementing and reversible counters.



The clock can be read from the program to access the current year, month, day, day of the week, and time (hours, minutes, and seconds). The clock is set from a Programming Device, such as a Programming Console. The Programmable Slave can also compensate for time inaccuracies of up to 30 seconds.

At its default settings, the Programmable Slave can be used as a

CompoBus/S (128 inputs and 128 outputs) Gateway. (Two words

An OMRON PT can be connected directly to the Programmable

Slave via a 1:1 NT Link for high-speed communications. (See

of memory are required for status.)

DeviceNet



Aessage

I/O links of up to 1,024 points (512 inputs and 512 outputs) can be created with the master. The input and output areas used in the I/O links can be allocated independently and the data areas starting addresses, and sizes of these read/write areas can be specified as required.

Explicit messages can be sent from the master to read or write data in any data area in the Programmable Slave.

RS-232C

NT Links



The communications I/O instructions TXD(48) and RXD(47) can be used in no-protocol mode to exchange data with standard serial devices. For example, data can be received from a bar code reader or transmitted to a serial printer. (See note 1.)

In High-speed Communications Mode, communications are possi-

ble over a distance of up to 100 m at a fixed cycle time of 0.8 ms.

When using Long-distance Communications Mode, the main line length can be extended to 500 m (communications cycle time: 6 ms). Also, versatile branching up to 200 m is possible using Spe-

A personal computer or OMRON Programmable Terminal (PT) connected in Host Link Mode can be used to read/write data in the Programmable Slave's I/O memory or read/change its operatina mode.

(256 points).

rations can be changed or expanded easily.

cial Flat Cable or 4-wire VCTF cable.

Note 1: Either a Peripheral/RS-232C Adapter or an RS-422/RS-232C Adapter is required for connection Note 2: Connection via a 1:N NT Link is not possible.

notes 1 and 2.)

CompoBus/S



The widely available VCTF (0.75) can be used for the communications cable. Alternatively, a Special Flat Cable can be used to enable simple one-touch expansion.

A wide range of models, including Remote I/O Terminals (transistor terminals with terminal-blocks or connectors), Analog Input Terminals, Analog Output Terminals, Relay Output Terminals, Waterproof Terminals, and Position Drivers are available as slaves.

CPM2C Expansion Units



The following mixed-I/O Units are available in addition to 8- and 16-point Input Units, and 8- and 16-point Output Units: 10-point Units: 6 inputs, 4 relay outputs 20-point Units: 12 inputs, 8 relay outputs 24-point Units: 16 inputs, 8 transistor outputs 32-point Units: 16 inputs, 16 transistor outputs



An Expansion I/O Unit with a terminal block providing 8 relay outputs is also available.



The Analog I/O Unit has two analog inputs and one analog output. (By combining the PID control instruction and PWM instruction, time-proportional control is possible.) Resolution: 1/6,000; Conversion period: 2 ms/point.



Temperature Sensor Units come in two types: Models with thermocouple inputs and models with platinum resistance thermometer inputs. Both types have two input points. Conversion period: 250 ms/2 points.



A Power Supply Unit with the same slim, compact design as the Programmable Slave is available. One-touch wiring is possible with the enclosed connector cable (23 cm). It can also be used as the power supply for indicators. (In this case, wiring must be performed by the user.)

General Specifications and Performance Specifications

Item	Specification			
Control method	Stored program method			
I/O control method	Cyclic scan method (Immediate refreshing can be performed with IORF(97).)			
Programming language	Ladder diagram			
Instruction length	1 step per instruction, 1 to 5 words per instruction			
Instructions	Basic instructions 14			
	Special instruction	s 105 instructions, 185 variations		
Execution time	Basic instructions	0.64 μs (LD instruction)		
	Special instruction	s 7.8 μs (MOV instruction)		
Program capacity	4,096 words			
Max. I/O capacity	CPU Unit only: 10 points Expansion I/O: 72 points (24-point Expansion I/O Unit X 3) (Up to 3 Expansion I/O Units can be connected.) CompoBus/S: 256 points (338 in total)			
Input bits	IR 00000 to IR 00915 (Bits not used for input bits can be used for work bits.)			
Output bits	IR 01000 to IR 01915 (Bits not used for output bits can be used for work bits.)			
CompoBus/S input bits	128 bits: IR 02000	to IR 02715		
CompoBus/S output bits	128 bits: IR 03000 to IR 03715			
Work bits	672 bits: IR 02800 to IR 02915 IR 03800 to IR 04915 IR 04000 to IR 04915 IR 20000 to IR 22715			
Special bits (SR area)	440 bits: SR 22800 to SR 25507			
Temporary bits (TR area)	8 bits (TR0 to TR7)			
Holding bits (HR area)	320 bits: HR 0000 to HR 1915			
Auxiliary bits (AR area)	384 bits: AR 0000 to AR 2315 These include the CompoBus/S slave status flags (AR 04 to 07).			
Link bits (LR area)	256 points: LR 000	00 to LR 1515		
Timers/Counters	256 timers/counters: TIM/CNT 000 to TIM/CNT 255 1-ms timers: TIMHH() 10-ms timers: TIMH1(15) 100-ms timers: TIM 1-s/10-s timers: TIM() Decrementing counters: CNT Reversible counters: CNTR(12)			
Data memory	Read/Write	2,048 words (DM 0000 to DM 2047) The Error Log is contained in DM 2000 to DM 2021.		
	Read-only	456 words (DM 6144 to DM 6599)		
	PC Setup	56 words (DM 6600 to DM 6655)		
DeviceNet slave functions	DeviceNet Remote I/O Link •Use up to 1,024 I/O points in the I/O Link. Explicit Message Communications •Any PC data area can be accessed from the master			

Connecting Cable (CPM2C-CN111, CS1W-CN114, or CS1W-CN118) is required

ations (peripheral/RS-232C) po

Communications Specifications DoviceNot

Devidentet					
Item	Specification				
Communications protocol	DeviceNet				
Connection form	Combination of multi-drop and T-branch connections (See note 1.)				
Baud rate	500 kbps, 250 kbps, or 125 kbps (switchable)				
Communications media	Special 5-wire cables (2 signal lines, 2 power lines, and 1 shield line)				
Communications distance	Baud rate	Network length (See note 2.)	Main line length	Total branch line length	
	500 kbps	100 m max. (See note 3.)	6 m max.	39 m max.	
	250 kbps	250 m max. (See note 3.)	6 m max.	78 m max.	
	125 kbps	500 m max. (See note 3.)	6 m max.	156 m max.	
Maximum according to	C4 (This figure	includes the moster			
of nodes	Maximum number of connectable slaves: 63.)				
Error controls	CRC error check, node address duplication check, scan list verification				

Note 1: Connect external terminating resistance Note 2: Distance between the farthest nodes.

Note 3: If thin, special cables are used for the main lines, this figure will be 100 m max.

Item		Specification		
Basic interrupt	Interrupt inputs	2 interrupts (Used for both counter mode interrupt inputs and quick-response inputs.)		
functions	Scheduled interrupts	1 interrupt		
High-speed	High-speed counters	1 counter (20 kHz single-phase or 5 kHz 2-phase)		
counter	Counter interrupts	1 interrupt (set value comparison or set-value range compariso		
functions	Interrupt Inputs (Counter mode)	2 interrupts (Used for both external interrupt inputs and quick-response inputs.)		
	Count-up interrupts	2 interrupts (Used for both external interrupt inputs and quick-response inputs.)		
Quick-response inputs		2 inputs (Used for both external interrupt inputs and counter mode interrupt inputs.) Min. input pulse width: 50 μs max.		
Pulse output		2 points with acceleration/deceleration, 10 Hz to 10 kHz each, and no direction control;1 point with trapezoid acceleration/deceleration, 10 Hz to 10 kHz, and direction control;2 points with variable duty-ratio outputs		
Synchroniz	ed pulse control	1 point		
Input time constant (ON response time = OFF response time)		Can be set for CPU inputs and Expansion Unit inputs only. (1 ms, 2 ms, 3 ms, 5 ms, 10 ms, 20 ms, 40 ms, or 80 ms)		
Clock		Equipped with clock (built-in RTC)		
Communications functions		Peripheral port: Supports Host Link, peripheral bus, no-protocol, or Programming Console connections. RS-232C port: Supports Host Link, no-protocol, 1:1 Link, or 1:1 NT Link connections.		
Memory protection		HR area, AR area, program contents, DM area contents, and counter values maintained during power interruptions.		
Memory ba	ckup	Non-volatile (flash) memory: Program, read-only DM area, and PC Setup		
		Memory backup (lithium battery; 2-year lifetime): DM area, HR area, AR area, and counter values		
Self-diagnostic functions		CPU errors (watchdog timer), memory errors, communications errors, setting errors, battery errors, and expansion I/O bus errors		
Program checks		No END instruction, programming errors (checked when operation is started)		
Programmin	g Programming Console	C200H-PRO27, CQM1-PRO01, or CQM1H-PRO01		
2 011000	Ladder Support Software (V3/V6)	IBM PC/AT or compatible		
	SYSMAC Support Software (V1 1)	IBM PC/AT or compatible		

CompoBus/S

Item		Specification					
Communications protocol		Special CompoBus/S protocol					
Coding method		Manchester coding					
Connecti	on form	Combination of multi-drop method and T-branch connections (See note 1.)					
Baud rate		High-speed Communications Mode: 750 kbps Long-distance Communications Mode: 93.75 kbps (See note 2.)					
Communi- cations cycle time	High-speed Communi- cations Mode	0.5 ms (with 8 input and 8 output slaves connected) 0.8 ms (with 16 input and 16 output slaves connected)					
,	Long-distance Communi- cations Mode	4.0 ms (with 8 input and 8 output slaves connected) 6.0 ms (with 16 input and 16 output slaves connected)					
Commun media	ications	2-wire cable (VCTF 0.75 X 2), 4-wire cable (VCTF 0.75 X 4), or Special Flat Cable					
Commun	ications	2-wire VCTF cable					
distance		Communications mode	Main line length	Branch line length	Total branch line length		
		High-speed Communications Mode	100 m max.	3 m max.	50 m max.		
		Long-distance Communications Mode	500 m max.	6 m max.	120 m max.		
		4-wire VCTF cable or Special Flat Cable					
		Communications mode	Main line length	Branch line length	Total branch line length		
		High-speed Communications Mode (See note 3.)	30 m max.	3 m max.	30 m max.		
		Long-distance Communications Mode (See note 4.)	Free branching (up to a total cable length of 200 m)				
Maximum nodes	n number of	32					
Error con	trol checks	Manchester code check, frame length check, and parity check					
Note 1: Conr	nect external tern	ninating resistance.					

Note 3: Writched using UM area setting. (Default setting: rov kops.) Note 3: If the number of slaves connected is 16 or less, the maximum main line length will be 100 m max and the maximum total branch line length will be 50 m max.

Note 4: There are no restrictions on the branching configuration, main line length, branch line length, or total branch line length. Connect external terminating resistance to the node farthest from the master