L4960

### 2.5A POWER SWITCHING REGULATOR

- 2.5A OUTPUT CURRENT
- 5.1V TO 40V OPUTPUT VOLTAGE RANGE
- PRECISE ( $\pm 2 \%$ ) ON-CHIP REFERENCE
- HIGH SWITCHING FREQUENCY
- VERY HIGH EFFICIENCY (UP TO 90\%)
- VERY FEW EXTERNAL COMPONENTS
- SOFT START
- INTERNAL LIMITING CURRENT
- THERMAL SHUTDOWN


## DESCRIPTION

The L4960 is a monolithic power switching regulator delivering 2.5 A at a voltage variable from 5 V to 40 V in step down configuration.
Features of the device include current limiting, soft start, thermal protection and 0 to $100 \%$ duty cycle for continuous operation mode.


The L4960 is mounted in a Heptawatt plastic power package and requires very few external components.
Efficient operation at switching frequencies up to 150 KHz allows a reduction in the size and cost of external filter components.

## BLOCK DIAGRAM



PIN CONNECTION (Top view)


## ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Value | Unit |
| :---: | :--- | :---: | :---: |
| $\mathrm{V}_{1}$ | Input voltage | 50 | V |
| $\mathrm{~V}_{1}-\mathrm{V}_{7}$ | Input to output voltage difference | 50 | V |
| $\mathrm{~V}_{7}$ | Negative output DC voltage | -1 | V |
|  | Negative output peak voltage at $\mathrm{t}=0.1 \mu \mathrm{~s} ; \mathrm{f}=100 \mathrm{KHz}$ | -5 | V |
| $\mathrm{~V}_{3}, \mathrm{~V}_{6}$ | Voltage at pin 3 and 6 | 5.5 | V |
| $\mathrm{~V}_{2}$ | Voltage at pin 2 | 7 | V |
| $\mathrm{I}_{3}$ | Pin 3 sink current | 1 | mA |
| $\mathrm{I}_{5}$ | Pin 5 source current | 20 | mA |
| $\mathrm{P}_{\text {tot }}$ | Power dissipation at $\mathrm{T}_{\text {case }} \leq 90^{\circ} \mathrm{C}$ | 15 | W |
| $\mathrm{~T}_{\mathrm{j},}, \mathrm{T}_{\text {stg }}$ | Junction and storage temperature | -40 to 150 | ${ }^{\circ} \mathrm{C}$ |

## PIN FUNCTIONS

| $\mathbf{N}^{\circ}$ | NAME | FUNCTION |
| :--- | :--- | :--- |
| 1 | SUPPLY VOLTAGE | Unregulated voltage input. An internal regulator powers the <br> internal logic. |
| 2 | FEEDBACK INPUT | The feedback terminal of the regulation loop. The output is <br> connected directly to this terminal for 5.1V operation; it is <br> connected via a divider for higher voltages. |
| 3 | FREQUENCY <br> COMPENSATION | A series RC network connected between this terminal and <br> ground determines the regulation loop gain characteristics. |
| 4 | GROUND | Common ground terminal. |
| 5 | OSCILLATOR | A parallel RC network connected to this terminal determines the <br> switching frequency. |
| 6 | SOFT START | Soft start time constant. A capacitor is connected between this <br> terminal and ground to define the soft start time constant. This <br> capacitor also determines the average short circuit output <br> current. |
| 7 | OUTPUT | Regulator output. |

THERMAL DATA

| Symbol | Parameter |  | Value |
| :---: | :--- | :---: | :---: |
| $R_{\text {th } j \text {-case }}$ | Thermal resistance junction-case | $\max$ | 4 |
| $\mathrm{R}_{\mathrm{th} \mathrm{j} \text {-amb }}$ | Thermal resistance junction-ambient | $\max$ | 50 |

ELECTRICAL CHARACTERISTICS (Refer to the test circuit, $\mathrm{T}_{\mathrm{j}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{i}}=35 \mathrm{~V}$, unless otherwise specified)

| Symbol | Parameter | Test Conditions | Min. | Typ. | Max. | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

DYNAMIC CHARACTERISTICS


ELECTRICAL CHARACTERISTICS (continued)

| Symbol | Parameter | Test Conditions | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## DC CHARACTERISTICS

| $\mathrm{l}_{10}$ | Quiescent drain current | 100\% duty cycle pins 5 and 7 open | $V_{i}=46 \mathrm{~V}$ | 30 | 40 | mA |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 0\% duty cycle |  | 15 | 20 | mA |
| $-17 \mathrm{~L}$ | Output leakage current | 0\% duty cycle |  |  | 1 | mA |

## SOFT START

| $\mathrm{I}_{6 \mathrm{SO}}$ | Source current |  | 100 | 140 | 180 | $\mu \mathrm{~A}$ |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{6 \mathrm{SI}}$ | Sink current |  | 50 | 70 | 120 | $\mu \mathrm{~A}$ |

## ERROR AMPLIFIER

| $\mathrm{V}_{3 \mathrm{H}}$ | High level output voltage | $\mathrm{V}_{2}=4.7 \mathrm{~V}$ | $\mathrm{I}_{3}=100 \mu \mathrm{~A}$ | 3.5 |  |  |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{~V}_{3 \mathrm{~L}}$ | Low level output voltage | $\mathrm{V}_{2}=5.3 \mathrm{~V}$ | $\mathrm{I}_{3}=100 \mu \mathrm{~A}$ |  |  | 0.5 |
| $\mathrm{I}_{3 \mathrm{SI}}$ | Sink output current | $\mathrm{V}_{2}=5.3 \mathrm{~V}$ | 100 | 150 |  | $\mu \mathrm{~V}$ |
| $-\mathrm{I}_{3 \mathrm{SO}}$ | Source output current | $\mathrm{V}_{2}=4.7 \mathrm{~V}$ | 100 | 150 |  | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{2}$ | Input bias current | $\mathrm{V}_{2}=5.2 \mathrm{~V}$ |  | 2 | 10 | $\mu \mathrm{~A}$ |
| $\mathrm{G}_{\mathrm{V}}$ | DC open loop gain | $\mathrm{V}_{3}=1 \mathrm{~V}$ to 3 V | 46 | 55 |  | dB |

OSCILLATOR

| $-I_{5}$ | Oscillator source current |  | 5 |  |  | mA |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- |

## CIRCUIT OPERATION (refer to the block diagram)

The L4960 is a monolithic stepdown switching regulator providing outputvoltages from 5.1 V to 40 V and delivering 2.5A.
The regulation loop consists of a sawtooth oscillator, error amplifier, comparator and the output stage. An error signal is produced by comparing the output voltage with a precise 5.1 V on-chip reference (zener zap trimmed to $\pm 2 \%$ ).
This error signal is then compared with the sawtooth signal to generate the fixed frequency pulse width modulated pulses which drive the output stage.
The gain and frequency stability of the loop can be adjusted by an external RC network connected to pin 3 . Closing the loop directly gives an output voltage of 5.1 V . Higher voltages are obtained by inserting a voltage divider.
Output overcurrents at switch on are prevented by the soft start function. The error amplifier output is initially clamped by the external capacitor $\mathrm{C}_{\text {ss }}$ and
allowed to rise, linearly, as this capacitor is charged by a constant current source. Output overload protection is provided in the form of a current limiter. The load current is sensed by an internal metal resistor connected to a comparator. When the load current exceeds a preset threshold this comparator sets a flip flop which disables the output stage and discharges the soft start capacitor. A second comparator resets the flip flop when the voltage across the soft start capacitor has fallen to 0.4 V .
The output stage is thus re-enabled and the output voltage rises under control of the soft start network. If the overload condition is still present the limiter will trigger again when the threshold current is reached. The average short circuit current is limited to a safe value by the dead time introduced by the soft start network. The thermal overload circuit disables circuit operation when the junction temperature reaches about $150^{\circ} \mathrm{C}$ and has hysteresis to prevent unstable conditions.

Figure 1. Soft start waveforms


Figure 2. Current limiter waveforms


Figure 3. Test and application circuit


C6, C7: EKR (ROE)
$\mathrm{L} 1=150 \mu \mathrm{H}$ at 5 A (COGEMA 946042)
CORE TYPE: MAGNETICS 58206-A2 MPP
$\mathrm{N}^{\circ}$ TURNS 45, WIRE GAUGE: 0.8mm (20 AWG)

Figure 4. Quiescent drain current vs. supply voltage (0\% duty cycle)


Figure 5. Quiescent drain current vs. supply voltage (100\% duty cycle)


Figure 6. Quiescent drain current vs. junction temperature ( $0 \%$ duty cycle)


Figure 7. Quiescent drain current vs. junction temperature ( $100 \%$ duty cycle)


Figure 10. Open loop frequency and phase responde of error amplifier


Figure 13. Switching frequency vs. R2 (see test circuit)


Figure 8. Reference voltage (pin 2) vs. $\mathrm{V}_{\mathrm{i}}$


Figure 11. Switching frequency vs. input voltage


Figure 14. Line transient response


Figure 9. Reference voltage versus junction temperature (pin 2)


Figure 12. Switching frequency vs. junction temperature


Figure 15. Load transient response


Figure 16. Supply voltage ripple rejection vs. frequency


Figure 17. Dropout voltage between pin 1 and pin 7 vs. current at pin 7


Figure 20. Efficiency vs. output current


Figure 18. Dropout voltage between pin 1 and 7 vs. junction temperature


Figure 19. Power dissipation derating curve


Figure 21. Efficiency vs. output current


Figure 22. Efficiency vs. output current


Figure 23. Efficiency vs. output voltage


## APPLICATION INFORMATION

Figure 24. Typical application circuit

$\mathrm{C}_{1}, \mathrm{C}_{6}, \mathrm{C}_{7}$ : EKR (ROE)
D 1 : BYW80 OR 5A SCHOTTKY DIODE
SUGGESTED INDUCTOR: $\mathrm{L}_{1}=150 \mathrm{\mu H}$ at 5 A
CORE TYPE: MAGNETICS 58206-A2 - MPP
${ }^{N} \times$ TURNS: 45 , WIRE GAUGE: 0.8 mm (20 AWG), COGEMA 946042
U15/GUP15: $\quad{ }^{\circ}$ TURNS: 60 , WIRE GAUGE: 0.8 mm ( 20 AWG), AIR GAP: 1 mm , COGEMA 969051.

Figure 25. P.C. board and component layout of the Fig. 24 (1:1 scale)


| Resistor values for <br> standard output voltages |  |  |
| :---: | :---: | :---: |
| $\mathbf{V}_{0}$ | $\mathbf{R 3}$ | $\mathbf{R 4}$ |
| 12 V | $4.7 \mathrm{~K} \Omega$ | $6.2 \mathrm{~K} \Omega$ |
| 15 V | $4.7 \mathrm{~K} \Omega$ | $9.1 \mathrm{~K} \Omega$ |
| 18 V | $4.7 \mathrm{~K} \Omega$ | $12 \mathrm{~K} \Omega$ |
| 24 V | $4.7 \mathrm{~K} \Omega$ | $18 \mathrm{~K} \Omega$ |

## APPLICATION INFORMATION

Figure 26. A minimal 5.1V fixed regulator; Very few component are required


Figure 27. Programmable power supply


[^0]APPLICATION INFORMATION (continued)
Figure 28. Microcomputer supply with $+5.1 \mathrm{~V},-5 \mathrm{~V},+12 \mathrm{~V}$ and -12 V outputs


## APPLICATION INFORMATION (continued)

Figure 29. DC-DC converter $5.1 \mathrm{~V} / 4 \mathrm{~A}, \pm \mathbf{1 2 V} / 2.5 \mathrm{~A}$; a suggestion how to synchronize a negative output


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L1, L3 = COGEMA 946042 (969051)
L2 = COGEMA 946044 (946045)
\(\mathrm{D}_{1}, \mathrm{D}_{2}, \mathrm{D}_{3}=\mathrm{BYW} 80\)
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Figure 30. - In multiple supplies several L4960s can be synchronized as shown


## APPLICATION INFORMATION (continued)

Figure 31. Regulator for distributed supplies


## MOUNTING INSTRUCTION

The powerdissipated in the circuit must be removed by adding an external heatsink.
Thanks to the Heptawatt package attaching the hetsink is very simple, a screw or a compression spring (clip) being sufficient. Between the heatsink
and the package it is better to insert a layer of silicon grease, to optimize the thermal contact, no electrical isolation is needed between the two surfaces.

Figure 32. Mounting example


HEPTAWATT PACKAGE MECHANICAL DATA

| DIM. | mm |  |  | inch |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A |  |  | 4.8 |  |  | 0.189 |
| C |  |  | 1.37 |  |  | 0.054 |
| D | 2.4 |  | 2.8 | 0.094 |  | 0.110 |
| D1 | 1.2 |  | 1.35 | 0.047 |  | 0.053 |
| E | 0.35 |  | 0.55 | 0.014 |  | 0.022 |
| F | 0.6 |  | 0.8 | 0.024 |  | 0.031 |
| F1 |  |  | 0.9 |  |  | 0.035 |
| G | 2.41 | 2.54 | 2.67 | 0.095 | 0.100 | 0.105 |
| G1 | 4.91 | 5.08 | 5.21 | 0.193 | 0.200 | 0.205 |
| G2 | 7.49 | 7.62 | 7.8 | 0.295 | 0.300 | 0.307 |
| H2 |  |  | 10.4 |  |  | 0.409 |
| H3 | 10.05 |  | 10.4 | 0.396 |  | 0.409 |
| L |  | 16.97 |  |  | 0.668 |  |
| L1 |  | 14.92 |  |  | 0.587 |  |
| L2 |  | 21.54 |  |  | 0.848 |  |
| L3 |  | 22.62 |  |  | 0.891 |  |
| L5 | 2.6 |  | 3 | 0.102 |  | 0.118 |
| L6 | 15.1 |  | 15.8 | 0.594 |  | 0.622 |
| L7 | 6 |  | 6.6 | 0.236 |  | 0.260 |
| M |  | 2.8 |  |  | 0.110 |  |
| M1 |  | 5.08 |  |  | 0.200 |  |
| Dia | 3.65 |  | 3.85 | 0.144 |  | 0.152 |



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[^0]:    $\mathrm{V}_{0}=5.1 \mathrm{~V}$ to 15 V
    $\mathrm{I}_{0}=2.5 \mathrm{~A}$ max
    Load regulation ( 1 A to 2 A ) $=10 \mathrm{mV}\left(\mathrm{V}_{0}=5.1 \mathrm{~V}\right)$

